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# physics754 – Problem Set 6

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Sorry for the landscape printing. The equations got pretty long and I did not want to break them all into several lines since they have so many parentheses.

## H.9: Schwarzschild trajectories given by the Jacobi method

I will omit the subscript  $q$  since there are no other velocities. Vectors in  $\mathbb{R}^3$  are typeset in bold serif italics.

### (a) Canonical momenta

The canonical momenta are:

$$p_i = \frac{\partial L}{\partial v^i} = -m \frac{1}{2f(\mathbf{q}, \mathbf{v}, q^0)} \left[ 2g_{0i}(q^0, \mathbf{q}) + 2g_{ij}(q^0, \mathbf{q})v^j \right].$$

I will assemble the hamiltonian from that. Since the function arguments to do change within the following calculations, I will just omit

them.  $f$  and  $g$  are still functions.

$$\begin{aligned}
H(\mathbf{q}, \mathbf{p}) &= [p_i v^i - L]_{v=v(\mathbf{q}, \mathbf{p})} \\
&= - \left[ \frac{m}{2f} [2g_{0i} + 2g_{ij} v^j] v^i - L \right]_{v=v(\mathbf{q}, \mathbf{p})} \\
&= - \left[ \frac{m}{f} [g_{0i} + g_{ij} v^j] v^i - L \right]_{v=v(\mathbf{q}, \mathbf{p})} \\
&= - \left[ \frac{m}{f} [g_{0i} v^i + g_{ij} v^i v^j - g_{00} - 2g_{0i} v^i - g_{ik} v^i v^k] \right]_{v=v(\mathbf{q}, \mathbf{p})} \\
&= - \left[ \frac{m}{f} [-g_{0i} v^i + g_{ij} v^i v^j - g_{00}] \right]_{v=v(\mathbf{q}, \mathbf{p})} \\
&= \left[ \frac{m}{f} [g_{00} + g_{0i} v^i] \right]_{v=v(\mathbf{q}, \mathbf{p})}
\end{aligned}$$

And that is the result from the problem set.

**(b) Differential equation for  $W$**

$$\begin{aligned}
m^2 &\stackrel{!}{=} \langle \partial W, \partial W \rangle \\
&= g^{00} [\partial_0 W] [\partial_0 W] + 2g^{0i} [\partial_0 W] [\partial_i W] + 2g^{ij} [\partial_i W] [\partial_j W] \\
&= g^{00} H^2 - 2g^{0i} H p_i + g^{ij} p_i p_j
\end{aligned}$$

I will now insert all the  $H$  and  $\mathbf{p}$ .

$$= \frac{m^2}{f^2} \left\{ g^{00} [g_{00} + g_{0i} v^i]^2 + 2g^{0j} [g_{00} + g_{0i} v^i] [g_{0j} + g_{ij} v^i] + g^{ij} [g_{0i} + g_{ki} v^k] [g_{0j} + g_{kj} v^k] \right\}$$

The terms in the big group have to equal  $f^2$  so that the result really becomes  $m^2$ . I will expand everything and see what cancels.

$$= \frac{m^2}{f^2} \left\{ g^{00} \left[ [g_{00}]^2 + 2g_{00}g_{0i}v^i + [g_{0i}v^i]^2 \right] + 2g^{0j} \left[ g_{00}g_{0j} + g_{00}g_{ij}v^i + g_{0j}g_{0i}v^i + g_{0i}v^i g_{kj}v^k \right] \right. \\ \left. + g^{ij} \left[ g_{0i}g_{0j} + g_{0i}g_{kj}v^k + g_{0j}g_{ki}v^k + g_{ki}v^k g_{lj}v^l \right] \right\}$$

Indices can now be raised, and some combinations of  $\mathbf{g}$  become  $\delta$ .

$$= \frac{m^2}{f^2} \left[ g_{00} + 2g_{0i}v^i + g^{00} [g_{0i}v^i]^2 + 2g_{00} + g_{00}v^0 + 2g_{0i}v^i + 2g_{0i}v^i v^0 + g_{00} + g_{k0}v^k + g_{k0}v^k + g_{kl}v^k v^l \right]$$

Using that  $v^0 = 1$  and renaming the dummy indices, a lot of this can be written more compact:

$$= \frac{m^2}{f^2} \left[ 5g_{00} + 8g_{0i}v^i + g^{00} [g_{0i}v^i]^2 + g_{kl}v^k v^l \right]$$

That is getting kind of into the desired direction, but not close enough.

### (c) Differential equation for $S(r)$

$\mathbf{g}$  is now diagonal. That makes the previous differential equation much easier.

$$m^2 = \langle \partial W, \partial W \rangle \\ = g^{00} \left[ \frac{\partial W}{\partial t} \right]^2 + g^{11} \left[ \frac{\partial W}{\partial r} \right]^2 + g^{22} \left[ \frac{\partial W}{\partial \theta} \right]^2 + g^{33} \left[ \frac{\partial W}{\partial \phi} \right]^2$$

The separation ansatz

$$W(t, r, \theta, \phi) = -Et + S(r) + l \arccos(y(\theta, \phi))$$

with

$$y(\theta, \phi) = \cos(\alpha) \cos(\theta) + \sin(\alpha) \sin(\theta) \sin(\phi)$$

and  $\alpha$  being a constant will give me chain rule contributions for the last two summands. I factor those out.

$$= g^{00} E^2 + g^{11} \left[ \frac{\partial S}{\partial r} \right]^2 + \left[ \frac{\partial W}{\partial y} \right]^2 \left[ g^{22} \left[ \frac{\partial y}{\partial \theta} \right]^2 + g^{33} \left[ \frac{\partial y}{\partial \phi} \right]^2 \right]$$

The derivative of arccos is given as:

$$\arccos'(x) = -\frac{1}{\sqrt{1-x^2}}.$$

With that:

$$\begin{aligned} m^2 &= g^{00} E^2 + g^{11} \left[ \frac{\partial S}{\partial r} \right]^2 + \frac{l}{1-y^2} \left[ g^{22} \left[ \frac{\partial y}{\partial \theta} \right]^2 + g^{33} \left[ \frac{\partial y}{\partial \phi} \right]^2 \right] \\ m^2 &= \frac{1}{1-\frac{r_s}{r}} E^2 - \left[ 1 - \frac{r_s}{r} \right] \left[ \frac{\partial S}{\partial r} \right]^2 + \frac{1}{r^2} \frac{l}{1-y^2} \left[ \left[ \frac{\partial y}{\partial \theta} \right]^2 + \csc(\theta)^2 \left[ \frac{\partial y}{\partial \phi} \right]^2 \right] \\ m^2 r^2 &= \frac{r^2}{1-\frac{r_s}{r}} E^2 - r^2 \left[ 1 - \frac{r_s}{r} \right] \left[ \frac{\partial S}{\partial r} \right]^2 - \frac{l}{1-y^2} \left[ \left[ \frac{\partial y}{\partial \theta} \right]^2 + \csc(\theta)^2 \left[ \frac{\partial y}{\partial \phi} \right]^2 \right] \end{aligned}$$

Now I separate the radial and angular parts.

$$\frac{r^2}{1-\frac{r_s}{r}} E^2 - r^2 \left[ 1 - \frac{r_s}{r} \right] \left[ \frac{\partial S}{\partial r} \right]^2 - m^2 r^2 = \frac{l}{1-y^2} \left[ \left[ \frac{\partial y}{\partial \theta} \right]^2 + \csc(\theta)^2 \left[ \frac{\partial y}{\partial \phi} \right]^2 \right]$$

Since both sides depend on different variables, they both have to equal a constant, that I will name  $c_1$ .

$$\frac{r^2}{1 - \frac{r_s}{r}} E^2 - r^2 \left[ 1 - \frac{r_s}{r} \right] \left[ \frac{\partial S}{\partial r} \right]^2 - m^2 r^2 = c_1$$

Now I can isolate  $S$ :

$$\left[ \frac{\partial S}{\partial r} \right]^2 = \frac{E^2}{\left[ 1 - \frac{r_s}{r} \right]^2} - \frac{c_1}{r^2 \left[ 1 - \frac{r_s}{r} \right]} - \frac{m^2}{1 - \frac{r_s}{r}}$$

Taking the square root, integrating ...

$$S(r') = \int_0^r dr' \sqrt{\frac{E^2}{\left[ 1 - \frac{r_s}{r} \right]^2} - \frac{c_1}{r^2 \left[ 1 - \frac{r_s}{r} \right]} - \frac{m^2}{1 - \frac{r_s}{r}}}$$

So the whole  $W$  now looks like this:

$$W = -Et + \int_0^r dr' \sqrt{\frac{E^2}{\left[ 1 - \frac{r_s}{r} \right]^2} - \frac{c_1}{r^2 \left[ 1 - \frac{r_s}{r} \right]} - \frac{m^2}{1 - \frac{r_s}{r}}} - l \arccos(y(\theta, \phi)).$$

#### (d) Trajectories

I am supposed to calculate  $P_2$ . I do not even know which of my parameters is  $Q_2$ . So my parameters are  $E$ ,  $c_1$  and I think that the  $l$  is yet another one of those parameters. But it could also be  $\alpha$ . One of those parameters is meaningless, and I should only get 3. That is what I read in (Kuypers 2010).

So I will just start with  $l$ . That might be  $Q_3$  or so.

$$\frac{\partial W}{\partial l} = \arccos(y) = -P_3$$

$$y = \cos(-P_3)$$

$$y = \cos(P_3)$$

$$\cos(\alpha) \cos(\theta) + \sin(\alpha) \sin(\theta) \sin(\phi) = \cos(P_3)$$

I can now separate  $\theta$  and  $\phi$  to either side of the equation.

$$\sin(\phi) = \cos(P_3) \sin(\alpha) \sin(\theta) - \cot(\alpha) \cot(\theta)$$

That gives me a relationship between  $\theta$  and  $\phi$ , but nothing with respect to  $r$ .

Then I tried to use  $c_1$  as the  $Q_2$ . The problem is that  $c_1$  does not occur in the angular term. So this will give me only a relationship from  $r$  with  $t$  at best.

$$\frac{\partial W}{\partial c_1} = -P_2$$

$$- \int dr \frac{1}{\sqrt{\frac{E^2}{\left[1 - \frac{r_S}{r}\right]^2} - \frac{c_1}{r^2 \left[1 - \frac{r_S}{r}\right]} - \frac{m^2}{1 - \frac{r_S}{r}}}} \frac{1}{r^2 \left[1 - \frac{r_S}{r}\right]} = -P_2$$

Even if I could solve this with respect to  $r$ , there would not be any angular part.

## References

Kuypers, Friedhelm (2010). *Klassische Mechanik*. 9th ed. Wiley-VCH Verlag GmbH & Co. KGaA. ISBN: 978-3-527-40989-1.