## **Disclaimer**

This is a problem set (as turned in) for the module physics615.

This problem set is not reviewed by a tutor. This is just what I have turned in.

All problem sets for this module can be found at http://martin-ueding.de/de/university/msc\_physics/physics615/.

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[disclaimer]

$$\frac{\partial \varphi_{i}}{\partial z_{i}} = \frac{1}{12} \begin{pmatrix} 1 & -i \\ 1 & -i \end{pmatrix}_{ij}$$
Construct chain rule. carefully.

$$M^{i}_{j} = \frac{\partial^{2} V}{\partial z_{i}} \frac{\partial^{2} V}{\partial \varphi_{a}} \frac{\partial \varphi_{b}}{\partial \varphi_{b}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{j}}$$

$$\frac{\partial \varphi_{a}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}}$$

$$\frac{\partial \varphi_{a}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}}$$

$$\frac{\partial \varphi_{a}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}}$$

$$\frac{\partial \varphi_{a}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial z_{i}} \frac{\partial \varphi_{b}}{\partial$$

$$=\frac{1}{2}\left(\frac{2m^2+\lambda V^2}{2\lambda V^2} \sin{(2\beta)}\right) \qquad 2\lambda V^2 \sin{(2\beta)}$$

$$2\lambda V^2 \sin{(2\beta)}$$

$$2\lambda V^2 \sin{(2\beta)}$$

$$2m^2-\lambda V^2 (4-2\cos{(2\beta)})$$

Part (b)

Extract: eigensystem with Modherotza.

$$\Lambda_1 = m^2 + \lambda V^2 \qquad \vec{V}_1 = \begin{pmatrix} \cot{(2\beta)} - \csc{(2\beta)} \end{pmatrix}$$

$$\Lambda_2 = v^2 + 3\lambda V^2 \qquad \vec{V}_2 = \begin{pmatrix} \cot{(2\beta)} + \csc{(2\beta)} \end{pmatrix}$$
In the limit  $\beta \to 0$  as in class these.
eigenvectors are mot sensible. One how to table the limit first and then find the eigenvectors. Those are then
$$\vec{V}_1^{(0)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \vec{V}_2^{(0)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$
The eigenvectors for  $\beta \neq 0$  are mot monocircular.

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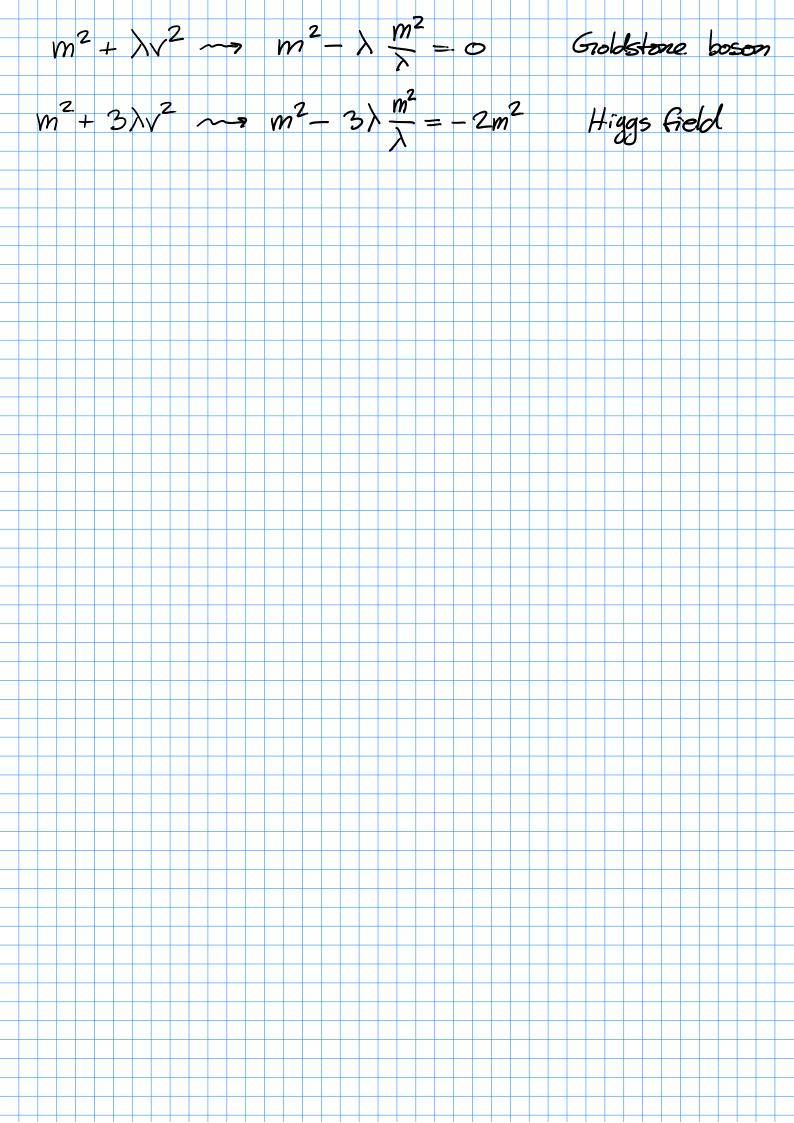
$$\vec{V}_2^{(0)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \vec{V}_2^{(0)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

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$$\vec{V}_2^{(0)$$

In general we have a matix M, eigenvector matix V and eigenvalue matix 1. We have:  $\mathcal{M}_{V_i} = \lambda_i V_i$ This needs to hold in the transformed basis as well. We have  $Ve_i = V_i$   $\Rightarrow$   $V^{-1}v_i = e_i$ Therefore it must be  $M = V \wedge V^{-1}$   $\rightleftharpoons V^{-1} \wedge V = \wedge$ We have V = (514(3) - 514(3))here. The O on the set is defined with  $\mathcal{U}^{2}O^{T}=O^{T}diag(m_{1}^{2},m_{2}^{2}).$ So OM20T is diagonal. That mains that O=VT and B=8. Also note that the minimum occurs at  $2m^{2}|\varphi| + 2\lambda |\varphi|^{3} = 0$  $|\varphi|\left(m^2 + \lambda |\varphi|^2\right) = 0$  $|\varphi|^2 - \frac{m^2}{\lambda} = V^2$ 



2 Gauge invariance in the Abelian Higgs Model Part (a.) We need a term with An AM in it for the mass. The second term in Equation (7) gives  $i(-i)g^2 A_n A_n \varphi^* \varphi = g^2 A^2 |\varphi|^2$ Inserting the ver and writing 1 2 g<sup>2</sup> v<sup>2</sup> A<sup>2</sup> gives  $m_A = \sqrt{2} gv$ . Part (b) The desired vertex is caused by some AAQ term in the Lagrangian. We need to find that. The field q consists of a constant and the two fields 12 and 5. We have in the (Dug) + (Dug) one tem with two A fields:  $9^2A^2|9|^2$ We do not insert the ver here, yet. We expand 92 A2 (Ve + 13) (Ve i/3 2+ is)

$$= g^{2}A^{2}\left[v^{2} + ve^{-i\beta}\frac{\eta + i\beta}{\sqrt{2}} + ve^{i\beta}\frac{\eta - i\beta}{\sqrt{2}} + \frac{\eta^{2} + \beta^{2}}{2}\right]$$
Face on there has:
$$g^{2}A^{2}V\int_{\overline{Z}} \left[\eta\left(e^{-i\beta} + e^{i\beta}\right) + i\delta\left(e^{-i\beta} - e^{i\beta}\right)\right]$$

$$2\cos(\beta) + i\delta\left(e^{-i\beta} - e^{i\beta}\right)$$

$$3\cos(\beta) + i\delta\left(e^{-i\beta} - e^{-i\beta}\right)$$

Part (c)

Equation (3) is

$$Q(x) = Veil^3 + \frac{1}{12} \left[ P_2(x) + i \cdot \mathbf{E}(x) \right]$$

The eigenvectors in  $P_2(x) = \mathbf{E}(x)$  are the physical fields:

$$G_1(x) = -\sin(f_3) P_2(x) + \cos(f_3) \mathbf{E}(x)$$

$$h(x) = \cos(f_3) P_2(x) + \sin(f_3) \mathbf{E}(x)$$

Here we want to go into the other direction.

So

$$\begin{pmatrix} P_1 \\ \mathbf{E} \end{pmatrix} = \begin{pmatrix} \cos \sin \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_1 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_1 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_1 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_2 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_3 \\ F_3 \end{pmatrix} \begin{pmatrix} G_1 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_2 \\ F_3 \end{pmatrix} \begin{pmatrix} G_2 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_3 \\ F_3 \end{pmatrix} \begin{pmatrix} G_3 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_3 \\ F_3 \end{pmatrix} \begin{pmatrix} G_3 \\ -\sin \cos \end{pmatrix} \begin{pmatrix} G_3 \\ -\cos \cos$$

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